

MOTOR PERFORMANCE		Winding codes	3UBN	3UDS		
		UNIT	WATER COOLING	WATER COOLING		
Tp	Peak torque	Nm	756	756		
Ti	Intermittent torque	Nm	678	674		
Tc	Continuous torque	Nm	516	512		
Ts	Standstill torque	Nm	421	417		
Ip	Peak current	Arms	47.4	94.9		
Ii	Intermittent current	Arms	42.5	84.0		
Ic	Continuous current	Arms	26.9	53.1		
Is	Standstill current	Arms	20.3	40.2		
ns	Rated low speed	rpm	0.14	0.14		
nm	Maximum speed without flux weakening	rpm	288	577		
nm,FW	Maximum speed with flux weakening	rpm	1050	1820		
ton,p	Maximum ON time for peak cycle	s	37	39		
ton,i	Maximum ON time for intermittent cycle	s	2.9	2.9		
Pp	Power dissipation @ Ip	W	9210	9440		
Pi	Power dissipation @ Ii	W	9990	9990		
Pc	Power dissipation @ Ic	W	4000	4000		
Td	Max. detent torque (average to peak)	Nm	3.0	3.0		

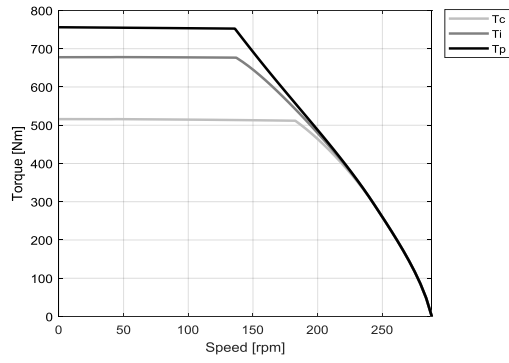
MOTOR SETTING		UNIT				
Kt	Torque constant	Nm/Arms	23.8	11.9		
Ku	Back EMF constant (*)	Vrms/(rad/s)	13.8	6.89		
Km	Motor constant	Nm/√W	12.1	11.9		
R20	Electrical resistance at 20°C (*)	Ohm	2.58	0.660		
Ld/Lq	Electrical inductance (*)	mH	22.6 / 17.5	5.65 / 4.39		
Isc	Maximum short-circuit current	Arms	21.3	42.6		
nb	Base speed	rpm	183	407		
nb,i	Base speed at intermittent duty cycle	rpm	137	317		
nb,p	Base speed at peak duty cycle	rpm	136	301		
nn	Rated speed	rpm	161	361		
Tn	Rated torque	Nm	513	497		
In	Rated current	Arms	26.6	51.2		
rth	Thermal time constant	s	127	127		
Rth	Thermal resistance	K/W	0.0269	0.0269		
2p	Number of poles	-	66	66		
J	Rotor inertia	kg·m²	0.265	0.265		
mr	Rotor mass	kg	16.2	16.2		
ms	Stator mass	kg	26.3	26.3		

MOTOR ENVIRONMENT		UNIT				
Udc	Nominal DC bus voltage	VDC	600	600		
Di	Intermittent duty cycle	%	40	40		
Dp	Peak duty cycle	%	5.0	5.0		
Sr	Rotor exchange surface	m²	0.087	0.087		
θamb	Ambient temperature	°C	20	20		
θmax	Maximum coil temperature	°C	130	130		
θw	Inlet water temperature	°C	20	20		
Δθw	Water temperature difference for Pc	K	5.0	5.0		
qw	Minimum water flow for Δθw	l/min	11	11		
Δpw	Max. pressure drop at qw	bar	0.4	0.4		

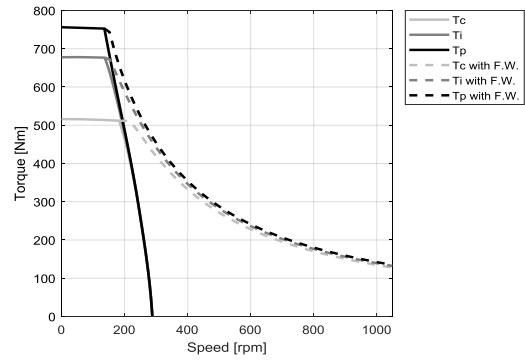
Notes: (*) terminal to terminal.
Hypotheses and tolerances are in ETEL Integration Manual.

Caution: Any use of the motor beyond speed/torque limit could lead to hazardous voltage and serious injuries. Customer is responsible for setting safeties/limitations that will keep the motor in its safe operating area. ETEL cannot be held responsible if the motor is used in an improper way.

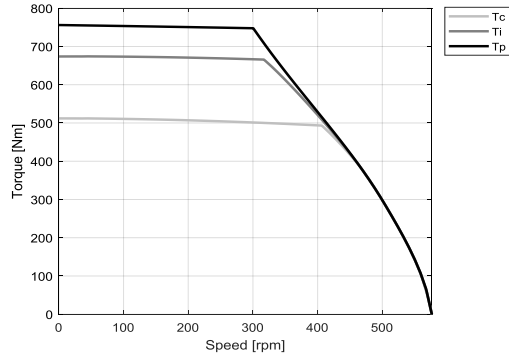
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